Simulation-based Development and Testing of Automated Driving

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Reference Scenarios and Traffic Spaces

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Agenda



- Motivation / Main Goal
- Scenario Description
- Traffic Spaces
- Reference Scenarios
- Road Generation Tool



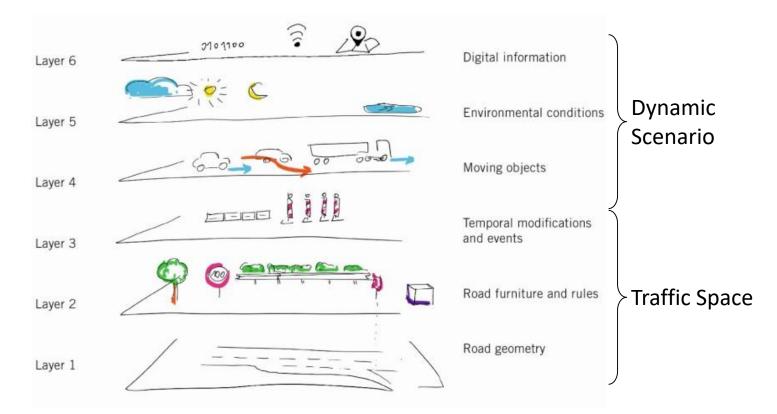
Build up a simulation environment

- to test and validate automated driving functions
- to test and validate **vehicle components**, e.g. environmental sensors
- to identify critical scenarios
- Stepwise approach with increasing complexity.

Basis for scenario description

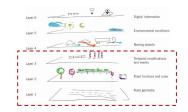


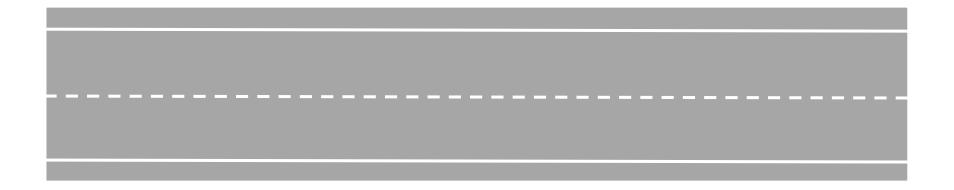
Pegasus 6-Layer Model



Straight road

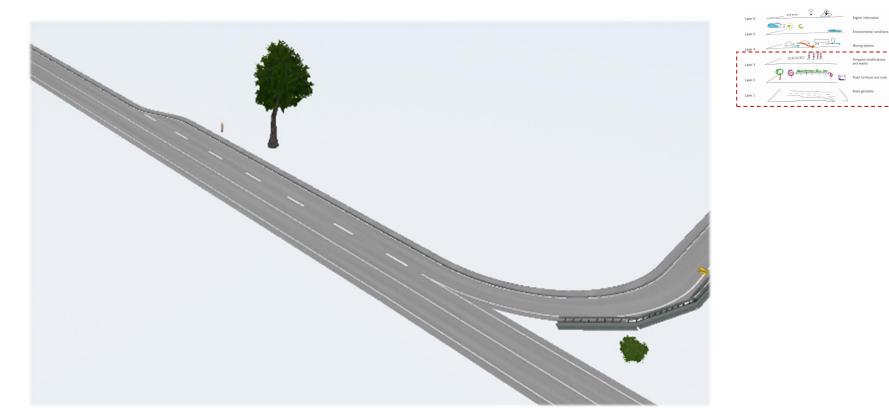






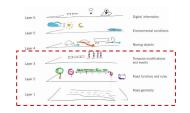
Arterial road with merging lane

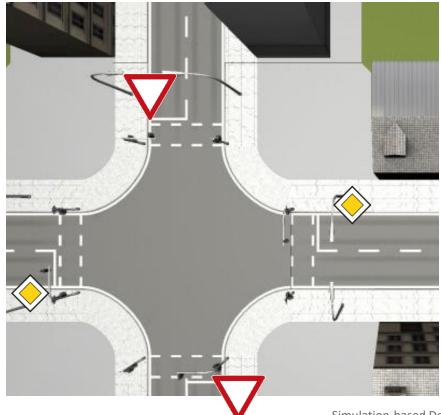




Simple intersection







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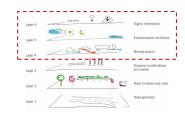
Complex intersection

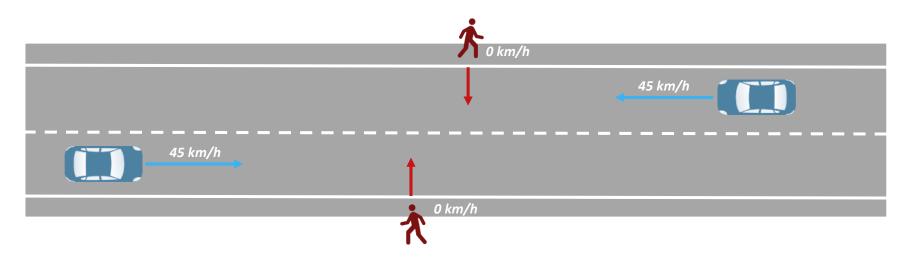




Crossing pedestrians

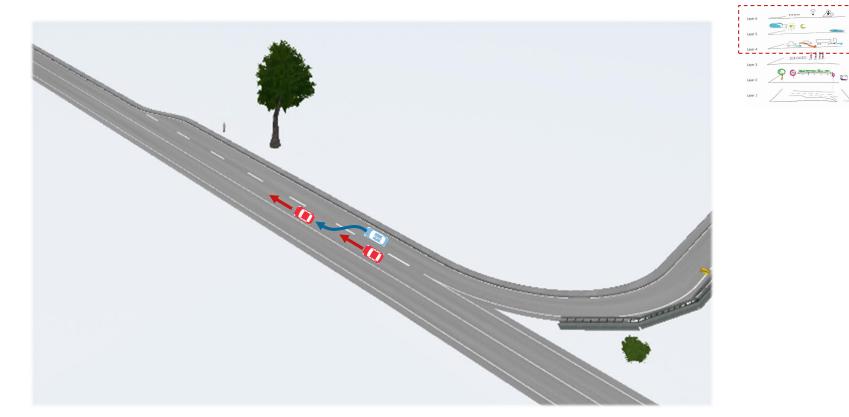






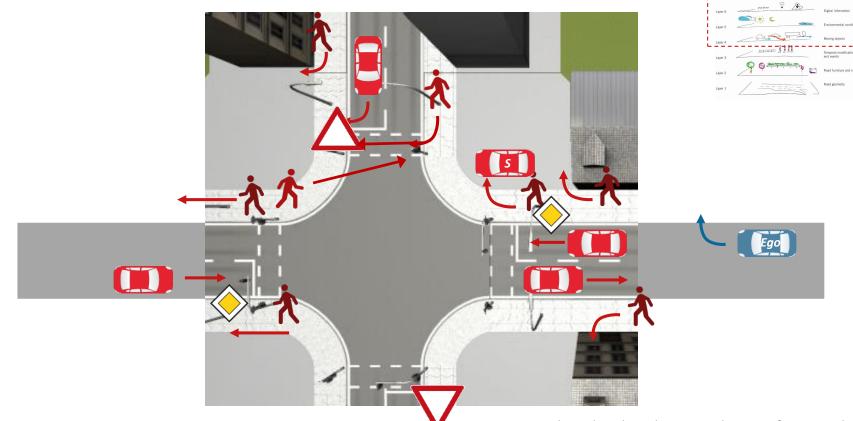
Merging into an arterial road





Right turn with crossing pedestrians





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Video Reference Scenarios – RS2





Left turn across oncoming traffic





ika - Road Generation Tool



- Existing standard formats for concrete scenarios
 - Static aspects: <a> ASAM OpenDRIVE

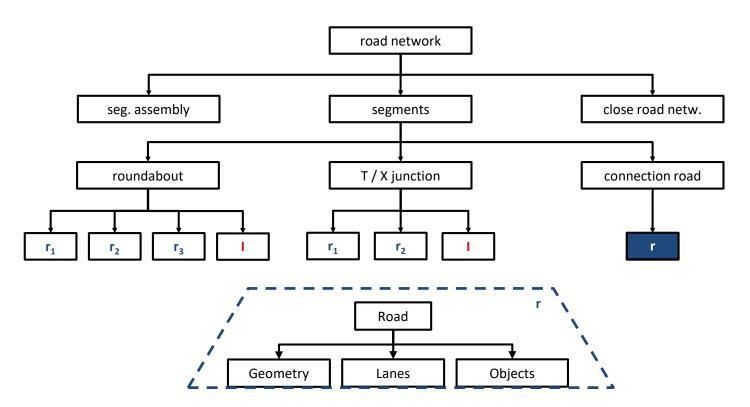
• Focus of this work

- Static part of scenario
- Find logical description similar to OpenDRIVE, but:
 - Non-redundant
 - Easy to vary
 - Modular approach
 - Oriented on real road construction
 - → Use of spiral, arcs, lines as geometric primitives only

Road network

Concept

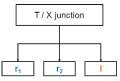


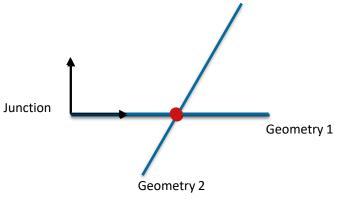


Road generation

Generation of Reference Lines of an X-Junction

- Two road definitions are required (r₁, r₂)
 - For simplicity: Two straight lines
- One intersection coupler (I) is needed
 - Orange dots indicate desired intersection point
 - r₁ is defined as reference segment
 - An angle for the junction is defined
 - Junction dimensions are specified (next slide)

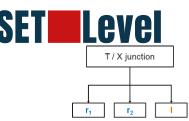


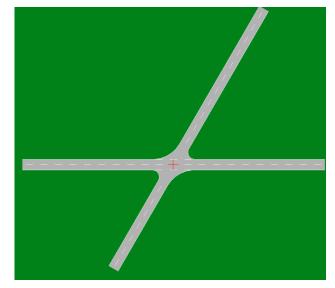


Road generation

Generation of Lanes and Connection Roads

- 1. Cut free the intersection area
 - Each direction to junction center can be specified
 - New reference lines are stored internally
- 2. Generate lanes of in-/outgoing roads
 - If nothing is specified, standard values are taken
 - Possible road classes: "main", "access"
- 3. Calculate connection roads inside the intersection
 - Angle continuous course (line + arc)
 - Every possible transition is generated
- 4. Generate lanes for those connection roads
 - "source" and "end" lane may have different width



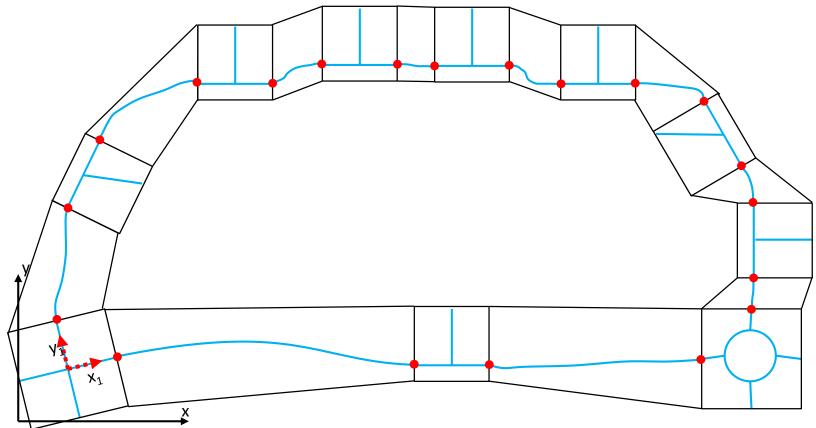


Visualized in ODR Viewer

Concept and Implementation



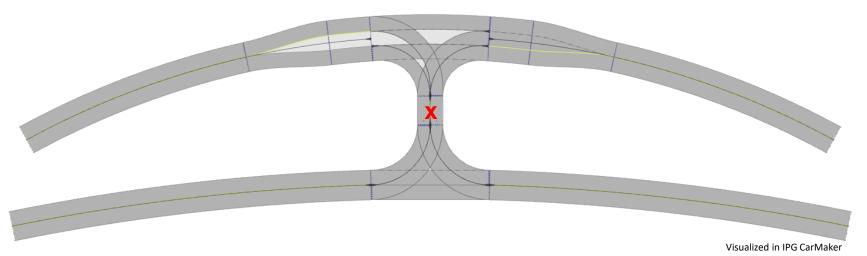
Road network creation



Examples



Two concatenated junctions



- Two T-junctions
- Definition only changed at two positions:
 - Arc's curvature
 - Flag for "additional left turn lane"
- \rightarrow The rest is generated and positioned automatically

	Lines of code
Logical Descr.	47
OpenDRIVE	937

Examples







Visualized in ODR Viewer

- Three intersections
- One roundabout
- One manual connection road
- Four automatically generated "close road network" roads

	Lines of code
Logical Descr.	219
OpenDRIVE	5477

Stochastic Variation

Motivation





Up to now lots of research regarding the variation of Layer 4 (6LM)

Among others: in PEGASUS project family



Hypothesis is that Layer 1 can challenge a VUT as well



Questions:

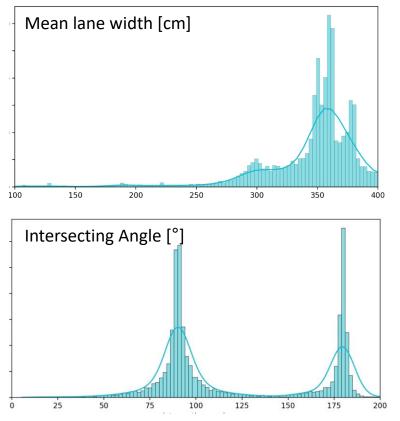
Which Properties of a road network are relevant? How can that be shown?

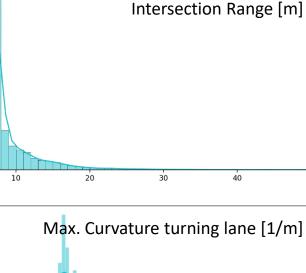


Analysis of real road networks to extract key performance indicators that can be used to parametrize the simulated road network

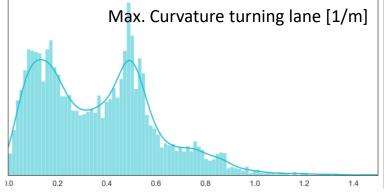
Stochastic Variation

Data Distribution of sampled Area (Berlin)





50



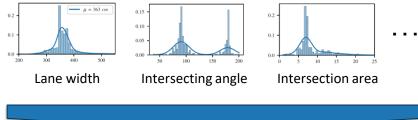
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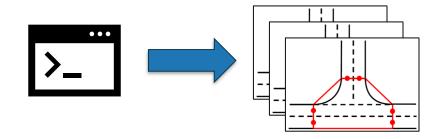
Stochastic Variation

Implementation

- Extended input format by random numbers
- Each value can be set as uniform and normal distribution



- Linear dependencies between variables can be realized as well
- \rightarrow Parts of this tool chain will be available on GitHub within this year





SET Level